Cell shape recognition and segmentation in fluorescence microscopy images

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ABSTRACT

Many cellular processes involve the translocation of proteins from the cytosolic region to the cortex of the cell and vice versa. The dynamics of such processes is typically investigated by fluorescence imaging of GFP-labeled versions of these proteins. Quantitative analysis of the resulting fluorescence images requires image segmentation procedures that identify the cell within the image and subsequently divide the cell into a cytosolic and a cortical region to monitor the temporal evolution of the fluorescence signals within these parts of the cell separately. Here, we present an image segmentation protocol that we have developed for this type of data analysis. It consists of noise reduction, normalization, and thresholding steps to generate masks that define the cytosolic and the cortical regions of a cell. Based on these masks, the desired fluorescence signals can be extracted from the confocal microscopy images.

Keywords: fluorescence microscopy, image processing, Dictyostelium

1 INTRODUCTION

The rapid progress of modern life science depends to a large extent on the use of advanced imaging techniques [1, 2]. In particular, the design of fluorescent markers that can be genetically encoded and expressed in vivo have enormously contributed to our understanding of subcellular processes. Together with the development of advanced fluorescence imaging techniques, like confocal laser-scanning microscopy, spinning-disk microscopy, or total internal reflection fluorescence (TIRF) microscopy [1], the green fluorescent protein (GFP) and its variants have established the basis for modern live cell imaging. The award of the Nobel Prize in Chemistry 2008 to Shimomura, Chalfie, and Tsien can be seen as the most widely recognized reference to this groundbreaking contribution. In addition, the advent of superresolution microscopy in recent years highlights that we have only seen the beginning of a technical revolution that is about to lead life science imaging beyond the diffraction limit of classical microscopy [3].

Many cellular processes show dynamic changes over time. In particular, the study of motile cells requires that image acquisition and processing adapt to an ongoing change in cell position and shape, so that each image of a time series has to be newly segmented. This is a key prerequisite to implement a quantitative analysis of the subcellular dynamics and distribution of fluorescent labels. For example, studies of the dynamics of the actin cytoskeleton are highly dependent on such techniques. While many researchers face these requirements and develop their own computer based tools to solve such problems, only very few of these algorithms have been made public in all detail. One of the commonly used programs that meet some of these requirements is QuimP (Quantitative Imaging for Membrane Proteins) [4]. QuimP is implemented as a set of plugins for ImageJ, one of the most widely used image processing tools [5]. QuimP uses an active contour to automatically detect the outline of a cell in order to quantify fluorescence signals along the cell membrane [6] and...
has recently been extended to correlate the cortical fluorescence signals with membrane movement, a typical problem in fluorescence microscopy of motile cells [7]. A similar problem has been addressed before based on morphodynamic profiling [8]. Here, we present an alternative, Matlab-based tool to quantify cortical and cytosolic fluorescence signals in motile cells.

2 MATERIALS AND METHODS

2.1 Cell culture

Dictyostelium discoideum cells expressing myosin II-GFP and LimEΔ-mRFP in an AX2 background were grown in HL-5 medium (Formedium, Hunstanton, UK) at room temperature (21 ± 2°C) in the presence of 0.01mg/mL G418 and 0.01mg/mL Blasticidin selection markers (Applichem, Darmstadt, Germany). Stimulation experiments were performed in 8 well slides (ibidi GmbH, Martinsried, Germany) with cGMP and cAMP (Sigma-Aldrich, Taufkirchen, Germany).

2.2 Microscopy and image acquisition

Images were recorded on an LSM 710 confocal laser scanning microscope (Carl Zeiss Microimaging, Jena, Germany). The green and red labels were excited at 488 nm (argon laser) and 561 nm (DPSS laser). Images were taken at a rate of one frame per second.

2.3 Image processing

Images were processed on a Linux workstation (OpenSUSE 11.3 64 bit) with an Intel Pentium T4400 CPU and 4 GB RAM. A custom-made Matlab program (Matlab R2008b, Mathworks, Ismaning, Germany) was used. The details of the image processing protocol are described below.

3 IMAGE SEGMENTATION PROTOCOL

In this section, we provide a detailed description of the segmentation procedure that we have developed to process fluorescence images of single amoeboid cells. In particular, this protocol was used to analyze dual color time lapse recordings obtained by laser-scanning confocal microscopy. The segmentation algorithm consists of three successive steps: noise reduction, normalization, and thresholding.

3.1 Three-dimensional noise reduction

The laser light typically used to excite GFP-derived fluorophores may cause considerable photo-damage in many live cell imaging applications. To reduce the harmful influence of the excitation light, its intensity and exposure time are reduced to the minimal possible values. This often results in noisy raw images that cannot be used directly for cell shape recognition. Thus, prior to image segmentation, the noise needs to be reduced. Typical strategies involve the application of blurring kernels that replace each pixel value by a local average of the pixel's surrounding. In this way, an increased continuity in brightness values and shape can be achieved. In order not to lose structural details of the image, the size of the blurring kernel has to be chosen large enough to efficiently reduce the noise on the pixel level but at the same time small enough so that structural features of the image are not erased.

The typical confocal microscopy images taken in the course of our live cell studies, have a resolution of 512 × 512 pixels, where 1 pixel correspond to 0.264 μm. They are usually recorded in time lapse sequences of 1 frame per second. In this case, a rectangular blurring kernel of 5 × 5 pixels has proven to be a good choice. Here, we would like to draw the attention to the point that noise reduction could be significantly improved, if not only the two-dimensional neighborhood within one time frame was taken into account, but the entire three-dimensional neighborhood involving also the neighboring pixels from the adjacent previous and following frames along the time coordinate. This three-dimensional blurring relies on a rectangular kernel of 5 × 5 × 5 pixels, where the third dimension extends along the time coordinate.

To demonstrate the effect of blurring, we present fluorescence images of a Dictyostelium cell that carries two fluorescent markers, a red fluorescent protein (mRFP) fused to LimEΔ and a green fluorescent protein (GFP) tagged to myosin II. Both proteins are associated with the actin cytoskeleton. The LimEΔ protein is known to colocalize with filamentous actin and has been established as one of the most widely used labels for polymeric actin structures in the cell [9]. Myosin II, on the other hand, is a motor protein that mostly localizes at the back of migrating amoeboid cells, where it mediates contraction of the cell cortex [10]. In Figure 1, the red (left) and green channels (right) of a dual color confocal microscopy image are displayed, showing the subcellular distributions of LimEΔ-mRFP and myosin II-GFP, respectively. In the top row, the raw data is shown, whereas the same images after application of three-dimensional blurring can be seen in the bottom row.

To illustrate the differences between two-dimensional and three-dimensional blurring, we present another example in Figure 2. Here, the application of different two-dimensional and
Figure 1 – Example of the application of a 3D blurring kernel to a dual color confocal recording. The images show a *Dictyostelium* cell that expresses mRFP fused to LimEΔ, a marker for filamentous actin, and GFP fused to myosin II. The red channel (actin) is shown on the left, the green channel (myosin) on the right. The top row shows the original raw images, whereas in the bottom row the same images after application of the 3D blurring kernel are displayed.

Figure 2 – Fluorescence image of a *Dictyostelium* cell expressing myosin II-GFP and LimEΔ-mRFP. The myosin distribution is shown, where the raw data (a) is compared to the results of applying (b) 3×3×3, (c) 5×5×5, (d) 5×5, (e) 10×10, and (f) 20×20 blurring kernels.
three-dimensional blurring kernels is compared. It can be clearly
seen that three-dimensional blurring results in a smoother im-
age without losing additional details as is the case for larger two-
dimensional kernels.

3.2 Normalization
Following noise reduction by three-dimensional blurring, the im-
ages are normalized. The overall sequence of operations involved
in this process is summarized as a flow chart in Figure 3.

![Flow chart summarizing the individual steps involved in normaliza-
tion of confocal microscopy images.](image)

In order to reduce computational time, between 1 and 5% of
the total number of pixels are randomly extracted from the image.
From the intensity values of these pixels, a histogram is com-
puted. If the number of extracted pixels is large enough, the his-
togram will resemble the intensity distribution of the total image.
(Note that this has only a minor effect on the computation time.
In cases where computational costs are of only secondary impor-
tance, the histogram can be also computed from the total num-
ber of pixels). In Figure 4 on top, an example for a normalized
histogram is shown. It was generated from a single cell fluores-
cence image, similar to the images displayed in Figure 1. Such
images are typically composed of a small number of bright pixels
that belong to the area covered by the cell, and a larger number
of dark pixels that are representing the background. The latter can
be clearly identified as a maximum in the histogram at low inten-
sity values. The smaller broad peak to the right of the background
(towards larger intensities) can be attributed to the pixels inside
the cell area.

![Figure 4](image)

To remove the background pixels, a cutoff value has to be de-
fined based on the histogram. The mean value,

\[ \langle f \rangle = \sum_{n=1}^{N} w_n f_n, \]

typically lies much higher than the background. It is computed
from the range of possible intensity values \( f_n \) and the normalized
histogram

\[ w_n = \frac{k_n}{\sum_{n=1}^{N} k_n}, \]

where \( k_n \) denotes the number of times that the intensity values
\( f_n \) occur in the image. To generate an appropriate cutoff value,
we rescale the histogram prior to normalization with an empirical
weighting function

\[ g_n = (f_{\text{max}} - f_n) h_n^2 \]
that gives more statistical weight to the low-intensity background part and to those parts that show a large probability. We thus obtain

\[ w_{BG,n} = \frac{g_n}{\sum_{n=1}^{N} g_n}, \]  

which is then used in Eq. (1) instead of \( w_n \). By adjusting the weighting function, the mean value taken over the weighted histogram can be shifted until it lies close to the maximum in the histogram at low intensity values, see Figure 4, bottom. This shifted mean value is then used as a cutoff to remove the background pixels from the entire image. Its position close to the maximum was empirically found to be optimal for removing the background from the image. In the case shown here, only the lowest intensity value is removed by background subtraction. Note that for other cases, where the background shows a larger average intensity, our procedure works equally well. Once the weighting function is optimized to find the cutoff value, it can be used to automatically remove the background from an entire sequence of images that were recorded in the course of a live cell experiment.

From the remaining pixels that do not belong to the background, the minimum intensity and the mean value are determined. They are used to normalize the full image according to

\[ f_{\text{norm}}(i,j) = \frac{f(i,j) - \min(f(i,j))}{\langle f(i,j) \rangle - \min(f(i,j))}, \]  

where \( f_{ij} \) are the intensity values of the individual pixels of the image. In the case of two (or more) simultaneously recorded fluorescence channels, each image is normalized separately according to the procedure described above. For the subsequent thresholding and segmentation the normalized images from the different channels are averaged for each time step. Note that if the different channels show strongly different noise levels, the quality of the combined image can be degraded. In such cases, the noise reduction in each channel has to be adapted individually. This, however, was not the case for our data.

### 3.3 Thresholding

With the normalized image as a starting point, we now apply a threshold to identify the region of the cell. We then perform the actual segmentation to divide the cell area into cortical and cytosolic regions. The individual steps of this procedure are schematically listed in Figure 5 together with an example image that we show for each of the intermediate stages of this sequence of image processing operations.

First, we apply the \texttt{MATLAB} function \texttt{imfill} to eliminate dark areas inside the cell. They frequently occur as a consequence of inhomogeneities in the distribution of fluorescent markers that are caused by organelles and other intracellular structures. Then the actual thresholding is performed. All pixels of the normalized image that show intensity values larger than 0.4 are taken as part of the cell. They are set to the value of 1. All remaining pixels shall belong to the background and are set to zero. In many cases, more than one cell can be found within the image. This will result in separate regions identified by the thresholding. Also, complex three-dimensional cell shapes may lead to several smaller disjunct regions when taking a single confocal cut through the cell. We apply the \texttt{MATLAB} function \texttt{bwlabel} to assign different integer numbers to these separate interconnected regions. The cell of interest is typically identified as the largest connected object among these regions. Alternatively, also the proximity of the regions to the center of the image may be employed as a criterion to select the cell area.

Start from preprocessed frame

\[ \downarrow \]

Apply \texttt{imfill} to fill holes (dark regions) inside the cell

\[ \downarrow \]

Apply a threshold of 0.4 to separate the cell from the surrounding (pixel intensities < 0.4)

\[ \text{(optional: perform additional erosion on noisy images)} \]

\[ \downarrow \]

Apply \texttt{bwlabel} to number connected regions

\[ \downarrow \]

Identify cell as the region with the largest area (optional: prefer region closest to the center of the image)

\[ \downarrow \]

Perform erosion to define masks of cortical and cytosolic regions

\[ \downarrow \]

Apply masks for cortical and cytosolic regions to the Original image to obtain the cortical and cytosolic fluorescence intensities

Figure 5 – Flow chart summarizing the individual steps involved in thresholding and segmentation of the cell into cortical and cytosolic regions.

Once the cell of interest is identified, its area is segmented into a cortical and a cytosolic part. This is achieved by eroding the cell area using the \texttt{MATLAB} function \texttt{imerode}. The remaining region is designated as the cytosolic part of the cell, whereas
the eroded zone around the border is taken as the cell cortex. The size of the eroded zone can be adapted by modifying the structuring element that `imerode` uses for the erosion process, see also the `MATLAB` documentation [11]. The resulting masks for the cortical and cytosolic regions are multiplied with the original raw image to extract the intensity values of the pixels that belong to the respective parts of the cell. From these pixels, averaged cortical and cytosolic fluorescence intensities can be computed for each time step of a confocal recording.

4 EXAMPLE

Let us now turn to an example to illustrate the type of analysis that can be performed based on the image processing protocol described above. It has been reported that the cAMP receptors of *Dictyostelium* have a reduced affinity also to certain cAMP derivatives and other cyclic nucleotides [12, 13]. In particular, the affinity to cGMP is very low, so that an upshift in extracellular cGMP is not expected to trigger the typical intracellular receptor responses, when supplied at physiological concentration levels.

To exemplify this fact, we have stimulated starvation-developed *Dictyostelium* cells that express myosin II-GFP and, as a marker for F-actin, also LimEΔ-mRFP, with a sudden step-like increase in the extracellular concentration of cGMP. This was achieved by adding the cGMP with a pipette to the cell culture that was plated in an 8 well slide. The concentration of the cGMP solution was chosen such that the final concentration in the culture well was 10 μM. The dynamics of both LimEΔ-mRFP and myosin II-GFP in response to the stimulus were simultaneously imaged by dual color laser scanning confocal microscopy. The resulting data was compared to cells of the same type that were exposed to a similar stimulus in the extracellular cAMP concentration to provide a reference case for a typical receptor response.

When exposed to an upshift in extracellular cAMP, starvation-developed *Dictyostelium* cells showed a boost in actin polymerization. This was reflected by the recruitment of LimEΔ-mRFP to the cell cortex, accompanied by a reciprocal depletion of the cytosolic fluorescence intensity. Similarly, also myosin II accumulated in the cell cortex, following a cAMP receptor stimulus. In Figure 6(a), the actin and myosin II signals can be seen, averaged over 13 cells. The fluorescence images were processed according to the segmentation protocol described above, and the cortical divided by the cytosolic fluorescence intensities are displayed for both labels. The peak responses of both proteins were reached about 25 s apart. This is in agreement with earlier results, where a similar time shift between the actin and myosin responses has been reported [15]. Note, however, that our data is less precise than the results presented in [15] because we have dropped the cAMP solution into the culture well with the developed cells, whereas Etzrodt and coworkers have used a flow chamber in order to precisely control the timing of the chemical stimulus.

In Figure 6(b), we show the response of the same type of cells to a cGMP stimulus. Data averaged over 10 single cells is displayed. A comparison with the cAMP-stimulation data in Figure 6(a) clearly reveals that a comparable cGMP stimulus does not trigger the typical cytoskeletal response within the cell. Neither an early boost in actin polymerization nor the later accumulation of myosin II in the cell cortex were observed, when the cells were exposed to extracellular cGMP. This confirms the earlier biochemical results on the much lower receptor affinity of cGMP as compared to cAMP [12, 13].

5 DISCUSSION

In this article, we have presented a protocol for cell shape recognition and segmentation of fluorescence images taken by laser-
scanning confocal microscopy. Our algorithm involves three successive stages, namely noise reduction, normalization, and thresholding of the image. It is specifically tailored to analyze protein translocation events between the cytosolic and the cortical regions of motile cells. Note that the three-dimensional noise reduction, as proposed here, may run into problems if the cell moves considerably over the time of the five adjacent frames that form the third dimension of the 3D blurring kernel. If the speed of the imaging system is sufficient, this problem can be circumvented by increasing the imaging frame rate. However, this requires that the photo-damage per frame is low enough in order to prevent rapid degradation of the sample. Alternatively, the number of time frames that are incorporated into the blurring kernel could be reduced. Instead, noise in the individual frames could be additionally reduced by increasing the exposure time.

Our segmentation algorithm is based on a thresholding procedure that only indirectly uses information from the image histogram (the background subtraction prior to image normalization relies on the histogram). This is in contrast to other commonly used histogram-based segmentation methods like Otsu’s method [16] or the Bi-Level Image Thresholding [17], where the threshold value is computed directly from a bimodal image histogram. In our case, we often encountered distorted unimodal histograms for which our method was found to give more reliable results as compared to methods optimized for clearly bimodal histograms. Alternative options are geometric active contour approaches like the Chan-Vese algorithm [18]. However, in the case of our fluorescence images that show a clearly defined cell (connected region of bright pixels) on a dark background, we obtained satisfactory results already with the simple global intensity threshold as described above.

We do not claim that the segmentation protocol described here is the only way to extract the desired information from the fluorescence images. Other approaches may yield similar results. In particular, there are software packages that show many user-friendly features like a graphical user interface (GUI) and compatibility with common image processing and graphics programs. A prominent example is the ImageJ plug-in QuimP, one of the most widely used tools for the processing of live-cell fluorescence images [4, 6]. Table 1 shows a comparison between features of the QuimP software and our segmentation protocol. QuimP combines a sophisticated image segmentation approach with the analysis of other cell parameters (shape, motion etc.) and integrates these functionalities into a user-friendly GUI that is amenable to a wide public of users from the life science community. On the other hand, our segmentation protocol is comparatively simple and implemented in a short MATLAB script. It thus addresses the different needs of the computer-educated user that demands a starting point to write his own custom-made image processing software, which he can readily change, extend, and adapt to his specific problems.

**Table 1 — Comparison between our segmentation protocol and the software package QuimP**

<table>
<thead>
<tr>
<th>Feature</th>
<th>Segmentation protocol presented here</th>
<th>QuimP</th>
</tr>
</thead>
<tbody>
<tr>
<td>Programming language</td>
<td>any MATLAB program</td>
<td>Java</td>
</tr>
<tr>
<td>Compatibility</td>
<td>medium</td>
<td>ImageJ</td>
</tr>
<tr>
<td>Degree of complexity</td>
<td>high</td>
<td></td>
</tr>
<tr>
<td>Flexibility</td>
<td>intensity threshold</td>
<td></td>
</tr>
<tr>
<td>Cell detection</td>
<td>temporal</td>
<td>Active contour</td>
</tr>
<tr>
<td>Resolution</td>
<td>no</td>
<td>spatial-temporal</td>
</tr>
<tr>
<td>Correlation with movement</td>
<td>no</td>
<td>yes</td>
</tr>
<tr>
<td>Graphical user interface</td>
<td>no</td>
<td>yes</td>
</tr>
</tbody>
</table>

We have demonstrated the function of our approach using cells of the social amoeba Dictyostelium discoideum, a popular model organism for the study of eukaryotic cell motility and chemotaxis. We used a construct that simultaneously expressed two fluorescent markers fused to proteins associated with the actin cytoskeleton. The temporal evolution of the cytosolic and cortical localization of these labels could be successfully followed over time to analyze the response of the cell to different extracellular ligands. We hope that our approach will make a useful contribution to the active and expanding area of live cell imaging applications at the interface of physics and biology.

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**REFERENCES**


CELL SHAPE RECOGNITION AND SEGMENTATION IN FLUORESCENCE MICROSCOPY IMAGES.


