

Partition of Online Social Networks using Simulations based on Chainable Processing Modules

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Abstract

Working with Complex Networks simulations focused on Online Social Networks (OSNs), we reached the limits of the architectural features of our software tool, because its project is not suitable to the inclusion of new resources as dynamic topological operations, on-the-fly visualizations, recognition of yet-to-be-developed algorithms, and concurrency programming support. We analyzed our current simulator and prepared a requirement list targeting to the development of a new one, privileging two features: flexibility and extensibility. We developed and applied the concept of independent processing modules that can form a processing chain according to Design Patterns and Java interface standards. These *Chainable Processing Modules* are the novelty and foundation of our architecture, that complies very well with the new simulator requirements. In this work, we present our software architecture and highlight its potential to help the development of open projects of simulators of any type of Complex Networks. Furthermore, we have implemented part of the proposed architecture and shown that new researches were fast carried out because of the reached flexibility.

Keywords: Simulation, Social Network Analyses, Software Architecture, Computational Data Analysis and Simulation in General Sciences.

1. Introduction

Computational simulation is an important tool for the study of complex networks in general [1, 2], and therefore it has a highlighted role to understand Online Social Networks (OSNs). These networks have been intensely

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37 researched in recent years, given their importance in today's world, as one
 38 can find in the following examples: [3, 4, 5, 6].

39 While we were working on a special case of partition of networks [7],
 40 we developed a piece of software that simulates the operation of common
 41 OSNs, named Demortuos[8]. Its main goal was the assessment of candidate
 42 algorithms of partitioning and it has an iterative graphical user interface, as
 43 exemplified in Fig. 1.

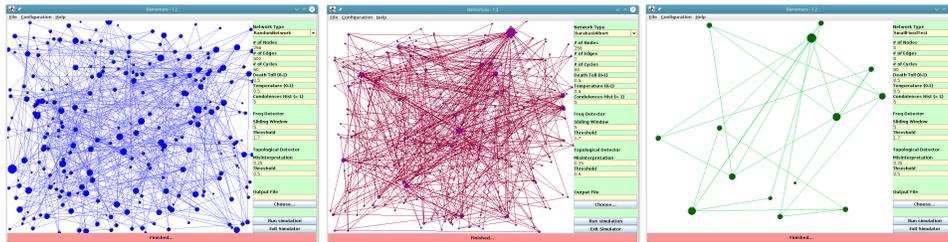


Figure 1: Three screenshots of *Demortuos* showing, from left to right, a random network with 128 nodes (average degree 2), a BA network with 128 nodes (average degree 2), and a small hand made test network with 14 nodes (average degree about 3).

44 Briefly, the program sequentially generates one of the possible realiza-
 45 tions of the network according to a user-selected model, simulates a number
 46 of message exchanges and operation days, and applies the algorithms under
 47 evaluation, collecting data for their posterior analyses. It had initially
 48 two available models: i) the Random Graph model after [9] (RN model);
 49 ii) the Scale-free model after [10] (BA model). Currently, there are addi-
 50 tional models available. *Demortuos* has built in Java, following the Design
 51 Patterns [11]. We specially used Strategy and Factory to improve its flexibil-
 52 ity and assesses three algorithms of partitioning. Because of its sequential
 53 processing, practical simulations are restricted to about 50,000 nodes per
 54 network.

55 Although the program performs very well its job, it arrived the time
 56 when some new research demands have arouse, bringing the software to its
 57 limits. For instance, currently investigations need more sophisticated models
 58 that include community structures as it is supposed to change the network
 59 dynamics. A review on this subject is found in [12]. Also, rewiring schemes
 60 need to be considered in the investigations because OSNs undergo changes
 61 in their links. Some considerations about rewiring process are found in
 62 [13, 14, 15]. Furthermore, we foresee new models for on-fly topology changes

Table 1: New architecture requirements

#	Requirement	Type
01	Very flexible general-purpose simulator for OSNs	mandatory
02	Automated simulation of several scenarios	mandatory
03	Compliance with Design Patterns standards	mandatory
04	Ability to deal with static and dynamic network models	mandatory
05	Acceptance of new network models	mandatory
06	Acceptance of new network operation patterns	mandatory
07	Recognition of yet-to-be-developed assessment algorithms	mandatory
08	Integrated simulation of topology evolution and network operation	mandatory
09	Entry points to pre- and post-processing algorithms	mandatory
10	Entry points to filters and general-purpose algorithms	mandatory
11	Entry points to on-the-fly data collection and storage	mandatory
12	Entry points to on-the-fly visualization	mandatory
13	Multithread support	mandatory
14	Compliance with Java 8 standards	optional
15	Compliance with Javadoc standards	optional
16	Interface with third-part programs	optional
17	Iterative and batch operation modes	optional
18	Parallel processing support	optional

63 that must be researched.

64 Therefore, we started the project of a new piece of software, for now
65 code-named DemortuosNG, that is intended to completely replace the pre-
66 vious tool. We target a full OSN simulator, not only a tester for partitioning
67 algorithms. So, the requirements undergone a significant change, as well as
68 the software architecture. In this paper, we present the proposed software
69 architecture as it brings a new approach to the design of this type of sim-
70 ulator. A point to be noticed is the chainable processing modules. These
71 modules permit that an arbitrary number of processing steps be combined
72 in a free and extensible fashion, pushing the flexibility of the simulator to
73 the next level. In the following section, we present the methodology for the
74 design of this new architecture.

75

76 2. Architecture

77 The objective of the new program is to produce a general-purpose OSN
78 simulator, because we look for a flexible tool, able to process several net-
79 work topology models under a diversity of operation patterns, algorithms,

80 and assessment procedures. Iterative and batch mode are desired features,
81 as well the support to execution threads and concurrency². Consequently,
82 we started with a requirement analyses that led us towards a list of
83 mandatory and optional features to the new simulator, as summarized in
84 Table 1.

85 From the requirements, we overlooked a whole new design to the simula-
86 tor. Its main feature is the use of a set of *chainable modules* inspired by the
87 Chain of Responsibility Design Pattern[11]. These modules are intended to
88 implement a common interface in order to be fully interchangeable. This
89 design provides the simulator with entry points for a yet-to-be-developed set
90 of network models, filters, and algorithms, as stated in the requirements of
91 the system.

92 The proposed architecture for DemortuosNG is shown in Fig. 2. Each
93 box indicates a module or a set of modules, whereas the arrows define the
94 main expected information flow. The *Control* module makes the overall
95 coordination of the system and exchanges pieces of information with virtu-
96 ally all other modules, but we omit its arrows to get a clean drawing. We
97 highlight that there is a relation among the modules and actual classes or
98 interfaces, but this is not a one-to-one map. Some modules may need several
99 classes to their implementation, whereas two modules may be jointed in one
100 class according to implementation decisions.

101 There are three modules groups: core simulation, input, and output.
102 They are intended to organize the architecture. The first one guides the
103 program concurrency, whereas the other two impose the production of a
104 set of interfaces to accommodate interchangeable modules, including the
105 adapters to communicate with other applications. In Fig. 2, the *Chainable*
106 *Processing* module is only a placeholder to the actual ones. Next, we present
107 the functionality of each module.

108 **Input Group:** all the modules of this group must implement a common
109 interface in order to be interchangeable; they are responsible to get config-
110 uration data such as simulation scenarios from diverse sources, as follows:

- 111 • Storage: from plain text files or database systems;
- 112 • GUI: from an interactive graphical user interface;
- 113 • Batch: from command line arguments or scripts files;
- 114 • Adapter: from a third-part application.

115 **Output Group:** all the modules of this group must implement a common

²Here, we adopt the [16]'s approach where threads optimize the time of one single CPU, whereas the concurrency concerns to a multicore/multi-CPU computer.

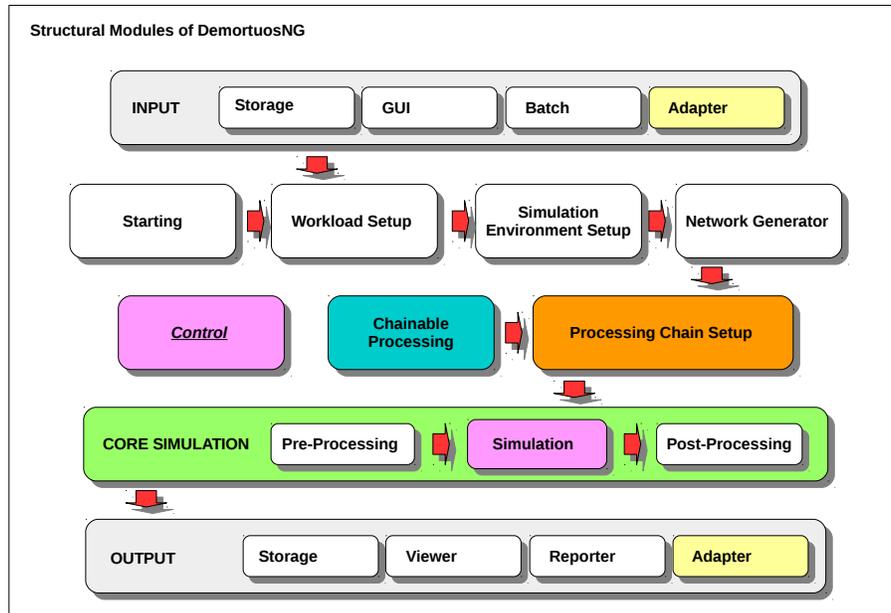


Figure 2: Overview of proposed architecture to OSNs simulators, presenting the structural modules; *Chainable Processing* is a placeholder to the actual modules; as *Control* exchanges data with all modules, its arrows were omitted.

116 interface in order to be interchangeable; they are responsible to collect data
 117 from the simulation process and present or save it to a destination as follows:

- 118 • Storage: to plain text files or database systems;
- 119 • Viewer: to an interactive graphical user interface;
- 120 • Reporter: to a structured high-level document;
- 121 • Adapter: to a third-part application.

122 Core Simulation Group: the modules of this group execute the processing
 123 steps of the simulation.

- 124 • Pre-processing: the one-time run procedures previous to the simulation, if
 125 any;
- 126 • Simulation: the simulation processing itself, according to the sequenced chain
 127 of processing modules;

- 128 • Post-processing: the one-time run procedures posterior to the simulation, if
129 any.

130 Loose modules: they have different roles as follows.

- 131 • Starting: system initialization tasks only concerned to the program;
132 • Workload Setup: load and configuration of the scenarios to be simulated;
133 • Simulation Environment Setup: setup of the run conditions, concurrency
134 mechanism, and correlated tasks;
135 • Network Generator: creation of one network realization according to the
136 chosen workload;
137 • Control: overall coordination of the system;
138 • Processing Chain Setup: creation of a sequence of chainable processing mod-
139 ules to be submitted to the Core Simulation;
140 • Chainable Processing: a placeholder for the actual modules (Fig. 3).

141 The Chainable Processing Modules are processing elements that may be
142 arranged in a chain sequence in order that the same object can be inspected
143 and processed by all of them. They are the key point of our architecture,
144 because they can include almost all types of algorithms in the simulator
145 in a standardized way. One network object pass through the chain in each
146 iteration undergoing different processing routines. The foreseen modules are
147 shown in Fig. 3 as follows.

- 148 • Filters: data selection, transformation, and conversion;
149 • General Algorithms: all-purpose processing;
150 • Internal Verification: integrity check for the simulation;
151 • Network: structural processing over network, as follows:
152 – Characterization: topological evaluation ³;
153 – Topology Dynamics: topological changes, rewiring;
154 • Assessment Algorithms: assessment of researches subjects;
155 • Operation: OSNs dynamics, as follows:
156 – Network Dynamics: non-topological changes;
157 – User Dynamics: user behavior or status changes;
158 – Message Dynamics: message exchange simulation.

159 Next, we discuss how the proposed architecture complies with the re-
160 quirements.

³See [17] for further details about characterization of complex networks.

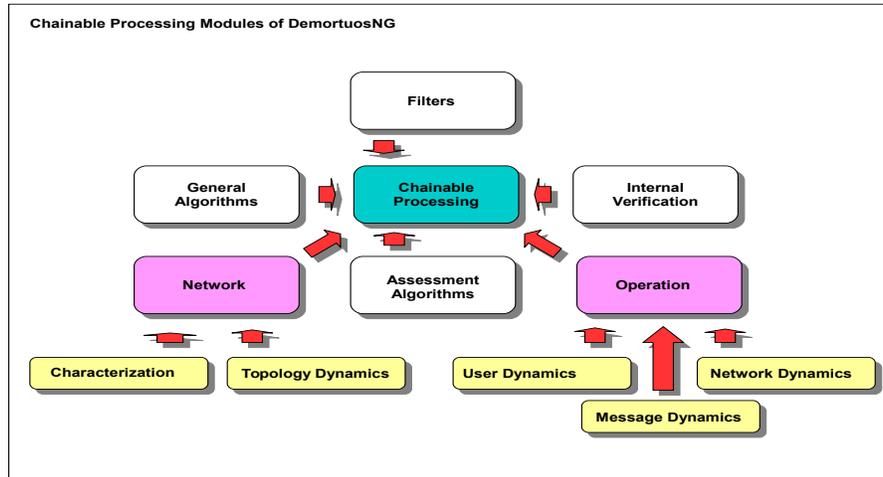


Figure 3: Overview of the *Chainable Modules* of the proposed architecture.

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- Very flexible general-purpose simulator for OSNs: the architecture was designed to perform all-purpose simulations of OSNs by means of the chainable modules that provide the desired level of flexibility; the input module permits a series of different sources for the configuration of the simulator, whereas the output modules are intended to be extensible classes, able to provide several forms to show the processing results, even for the intermediate ones.
 - Automated simulation of several scenarios: the architecture was planned to support multiple instances of the core simulation module; it is intended to automatically run several scenarios without user intervention.
 - Compliance with *Design Patterns*, Java 8, and Javadoc standards: although the compliance is deeply related to the detailed project and codification of Java classes, the proposed architecture fully supports these standards.
 - Ability to deal with static and dynamic network models: the independence among the network generator modules and the simulation core allows the system works with the both types of networks.
 - Acceptance of new network models and operation patterns: the use of independent extensible modules for generation, evolution, and simula-

181 tion of networks provides this compliance.

- 182 • Recognition of yet-to-be-developed filters, general-purpose and assess-
183 ment algorithms: the chainable modules may be extended to imple-
184 ment a new functionality; thus, it is possible to include new code in a
185 standardized way as soon it becomes available.
- 186 • Integrated simulation of topology evolution and network operation:
187 the architecture does not impose the separation between these two
188 tasks as in the previous software tool, so it is possible to integrate
189 them according to the user needs.
- 190 • Entry points to pre- and post-processing algorithms: they are located
191 in the Core Simulation group, as specific processing objects.
- 192 • Entry points to on-the-fly data collection, visualization, and storage:
193 the chainable extensible output modules provide support for these re-
194 quired operations.
- 195 • Multithread and parallel processing support: the core simulation mod-
196 ule may be parallelized to simultaneously run different scenarios and/or
197 repetitions related to a configuration set of parameters; the actual im-
198 plementation will choose the most suitable technique.
- 199 • Interface with third-part programs: there is a prevision for Adapters
200 in both input and output modules, then it is possible to write interface
201 code to other programs.
- 202 • Iterative and batch operation modes: this feature is supported by the
203 independence between the input modules and the processing ones.

204

205 **3. Results**

206 We have started the development of the new tool using the proposed
207 architecture. As we want the benefits of this approach as soon as possible,
208 we are still using extensive portions of the old software code to support the
209 inclusion of the new features, towards a complete replacement process.

210 Thus, we redesigned some classes from scratch according with the pro-
211 posed architecture and we built a set of new classes that implement addi-
212 tional network models. The first one was that presented by [18], henceforth
213 SZW model. The SZW model generates scale-free networks with commu-
214 nity structure, starting with an arbitrary number of initial high-connected
215 small networks. Because the originating configuration of these initial net-
216 works is not specified by the model, it was possible to implement several

Table 2: OSNSim Standard - Part I - 2016

Parameter	Scenario 01	Scenario 02	Scenario 03	Scenario 04	Scenario 05	Scenario 06
Model	RN; SF	RN; SF	RN; SF	RN; SF	RN; SF	RN; SF
Order	5K	5K	5K	20K	20K	50K
Average node degree	10; 100	10; 100	500	100	500	500
Cycles	30; 90; 360	30; 90; 360	30; 90; 360	30; 90; 360	30; 90; 360	30; 90; 360
Mortality rate	0.050; 0.500	0.005; 0.050	0.005; 0.050	0.005; 0.050	0.005; 0.050	0.005; 0.050
Inactivity rate	0.50	0.05	0.05; 0.20	0.05; 0.20	0.05; 0.20	0.05; 0.20
Temperature	0.0; 0.5; 1.0	0.0; 0.5; 1.0	0.0; 0.5; 1.0	0.0; 0.5; 1.0	0.0; 0.5; 1.0	0.0; 0.5; 1.0
Combinations	72	72	72	72	72	72

217 variations in the subject. For instance, the initial networks can be random,
 218 scale-free, hand-made, etc. In the Fig. 4 we show one realization of this
 219 model, compared to an BA network with equal dimensions.

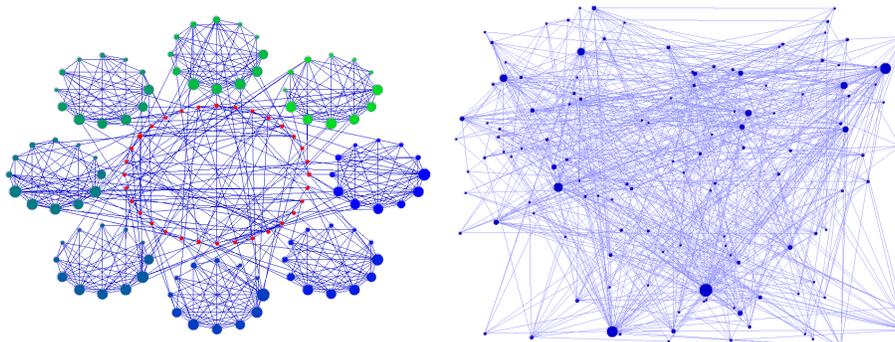


Figure 4: Comparison between two networks of the same order and size. The one at left is an SZW uncorrelated scale-free with communities, based in the proposal of [18] – the picture emphasizes the initial communities that are BA networks; the one at right was a BA network generated according to the [10]’s model.

220 As supposed, the presence of communities in the SF network changed
 221 the simulation results. Preliminary data indicates that the efficiency of the
 222 partition algorithms has an improvement, as exemplified by the simulation
 223 of a subset of the Scenario 4 of OSNSim standard [19], highlighted in Table
 224 2.

225 In Table 3 it is possible to notice the improvement of efficiency, rang-
 226 ing from 0.067 to 0.268. The higher Temperature, the higher the volume
 227 of messages in the network. So, the algorithm performs better when the
 228 Temperature parameter is high, independently of the network model.

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Table 3: Efficiency of a partition algorithm for OSNs based in message frequency over BA (without communities) and SZW (with communities) network realizations. The both networks have 20,000 nodes and average degree 100, according to Scenario 4 of OSNSim standard.

Mortality Rate	Temperature	BA Model	SZW Model	Abs Diff
0.005	0.0	0.062	0.129	0.067
0.005	0.5	0.151	0.282	0.131
0.005	1.0	0.290	0.558	0.268
0.050	0.0	0.092	0.147	0.055
0.050	0.5	0.173	0.302	0.129
0.050	1.0	0.285	0.540	0.255

4. Conclusion

We proposed a software architecture to OSNs simulators, based in our previous experience with this type of program. As our goal is to produce a general-purpose OSN simulator, we prepared a list of ambitious requirements for the software development, which are as general as possible, but they presuppose an actual object oriented implementation. Although we are going to make our code using Java, the architecture is suitable for C++ as well.

We presented a new, modular, flexible, and extensible software architecture that has chainable processing modules as its strongest novelty. These modules impose a particular model of operation to the simulator, that supports the inclusion of a yet-to-be-developed functionality set. Thus, our architecture may be used to create open OSNs simulators and to inspire the design of other simulators.

Currently, we are validating the proposed architecture, starting the project of the actual Java classes, and implementing the network generating classes. Initial simulations has used extensive portions of the previous version of Demortuos to allow early tests.

As we already have implemented additional models, we showed that the community structure within a scale-free network changes the behavior of algorithms in that network. We exemplified this change presenting the efficiency increase of partitioning algorithms designed to OSNs. Our actual goal is to finish the new software according to our proposed architecture to improve largely our OSNs analysis capacity.

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